

DESIGN and VALIDATION of RELIABLE NETWORKED SYSTEMS

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Overview



- DEPEND hierarchical framework for design and evaluation of dependable systems
 - the complete case study to demonstrate the capabilities of the hierarchical simulation methodology for accurate fault modeling
 - target system: Myrinet, high-speed network
- Validation of the simulation results via actual fault injection to the same target system using N-FTAPE
- Collaboration with JPL



DEPEND: A Hierarchical Framework for Design of Dependable Systems

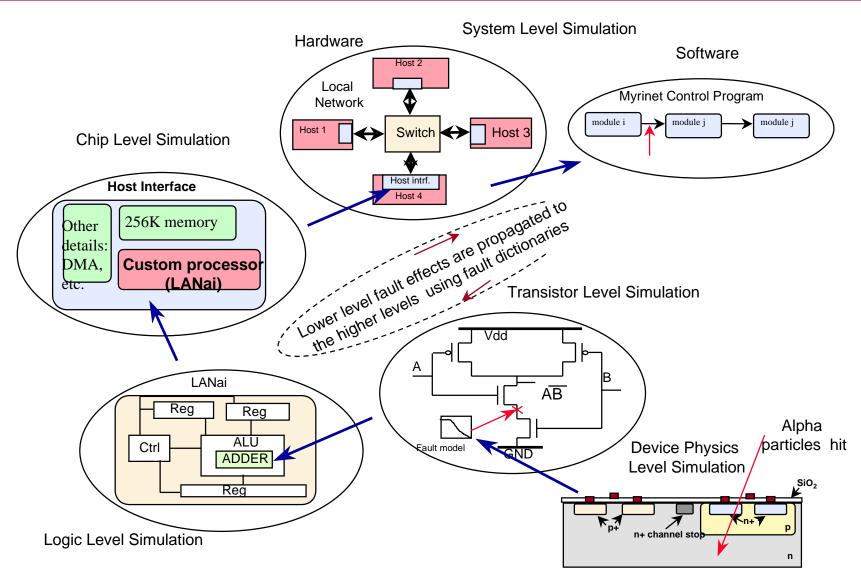
Issues



- Conventional methods of simulated fault injection employ random bit-flipping at lower levels (e.g., gate or register) and evaluate resulting effects at higher levels (e.g., subsystem or system).
- Not based on a physical fault model and may lead to an unrealistic predictions at the system level.
- Accurate results possible by:
 - generating transient faults based on a physical model that depicts transistorlevel effects of cosmic radiation, current and voltage spikes, and bridging transients
 - propagating the effects of derived transients through to the system level.

Hierarchical Fault Modeling- LANai Processor

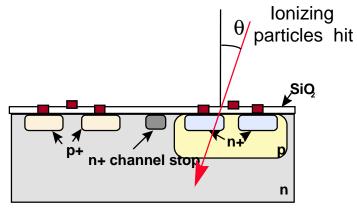




Transistor Level Simulation



DESSIS Simulation

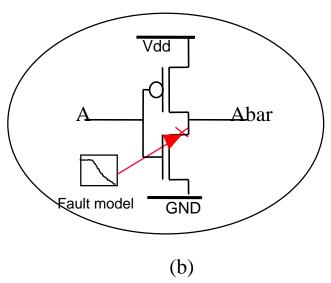


 θ - is the angle of incidence

(a)

(a) Ionizing Particle Incident on a CMOS Inverter,

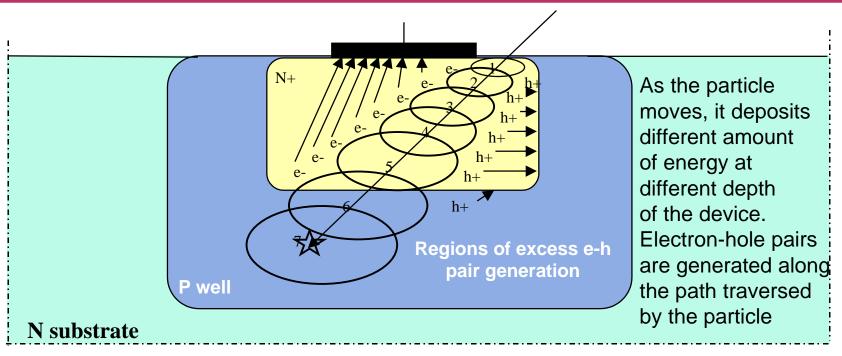
HSPICE Simulation

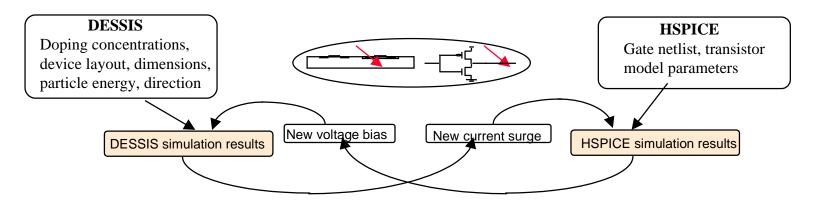


(b) Inverter Circuit with Current Burst Injection at the Output Node

Injection Process in the Reverse Biased Junction of NMOS Transistor

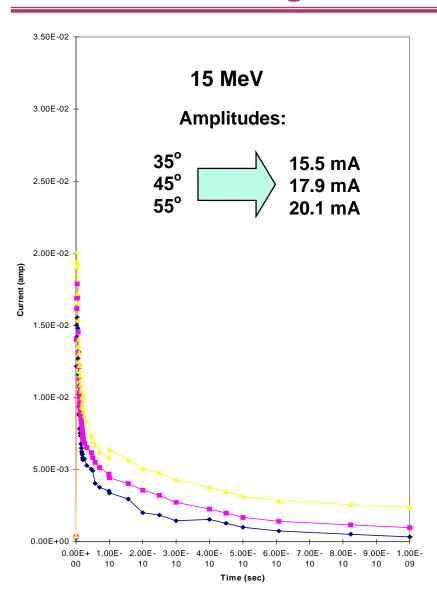


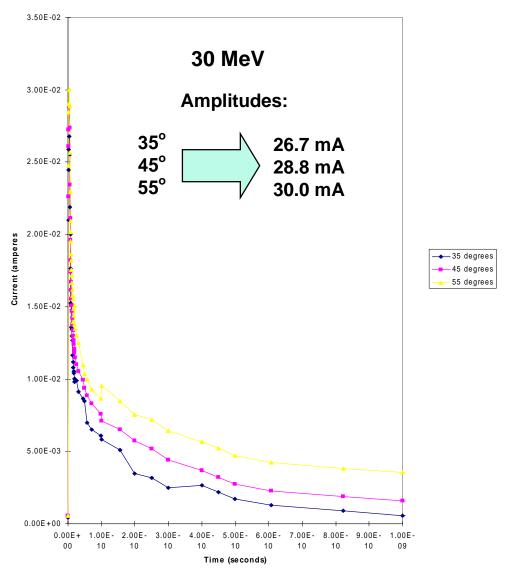




Primary Fault Models Derived from Mg12+ Ion

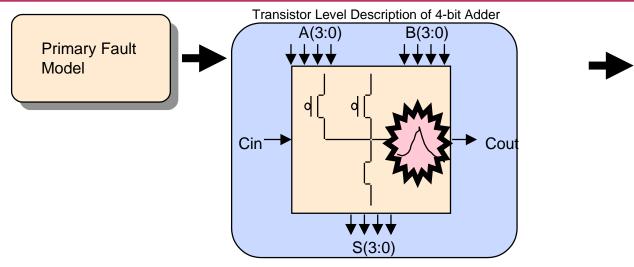




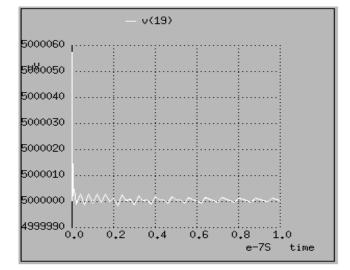


Circuit Level Simulation

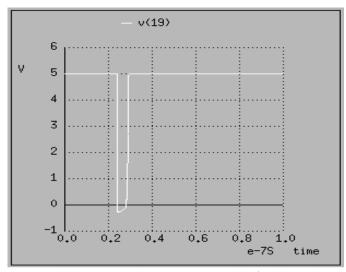




For all nodes, for all input combinations



Voltage at an inverter output without fault injection



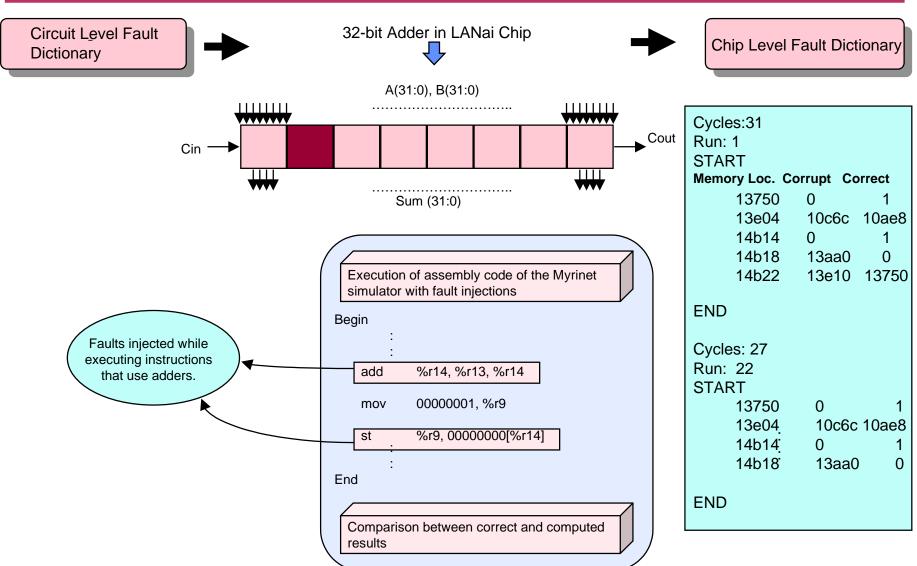
Voltage at an inverter output with fault injection (latching at 25ns)

Circuit Level Fault Dictionary

```
B Cin
Input 0000 0000 0
   S Cout
            34%
            39%
            7%
   F-F- F
            20%
Input 0000 0000 1
   ---F F
            10%
   -F-F -
            2%
   -FF- -
            52%
   -FF- F
            13%
   F-FF F
            23%
Input 1111 1111 1
            23%
            1%
            9%
            33%
   -FFF -
            33%
   FFFFF
            1%
```

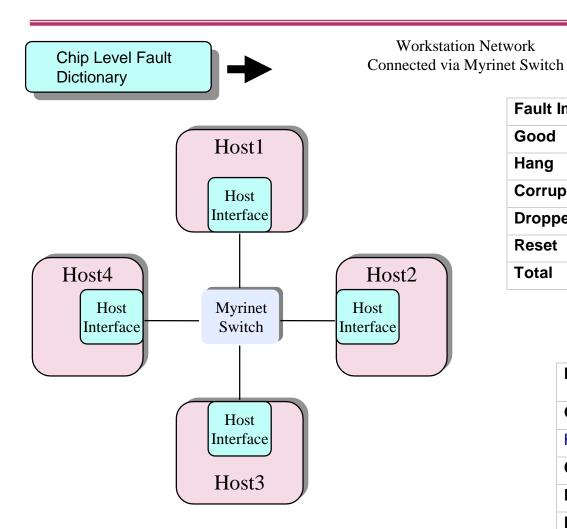
Chip Level Simulation





System Level Simulation







Normal/Abnormal System Behavior

Fault Impact	35 degrees	45 degrees	55 degrees
Good	92 (56%)	280 (56%)	269 (55%)
Hang	40 (25%)	82 (16%)	81 (17%)
Corrupted	9 (6%)	40 (8%)	41 (8%)
Dropped	22 (13%)	98 (20%)	97 (20%)
Reset	0 (0%)	0 (0%)	0 (0%)
Total	163 (100%)	500 (100%)	487 (100%)

×				
Fault Impact	Without recovery	With recovery		
Good	280	327		
Hang	82	22		
Corrupted	40	40		
Dropped	98	111		
Reset	0	0		
Total	500	500		

Hierarchical Simulation - Conclusions



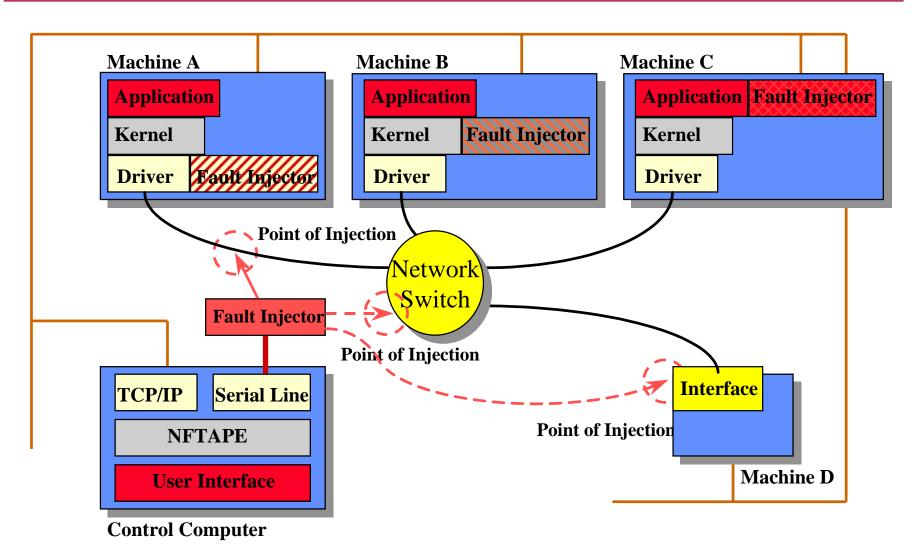
- The hierarchical simulation approach offers:
 - injection of representative faults
 - system evaluation on different abstraction levels (from device level to system level)
 - rapid propagation of low level transients through the system with realistic workloads
 - high confidence in the evaluation and validation results
- The approach is being integrated to the DEPEND framework for designing and validation of dependable computing and communication systems.
- Web site: http://www.crhc.uiuc.edu/DEPEND



N-FTAPE: Network Fault Tolerance and Performance Evaluator

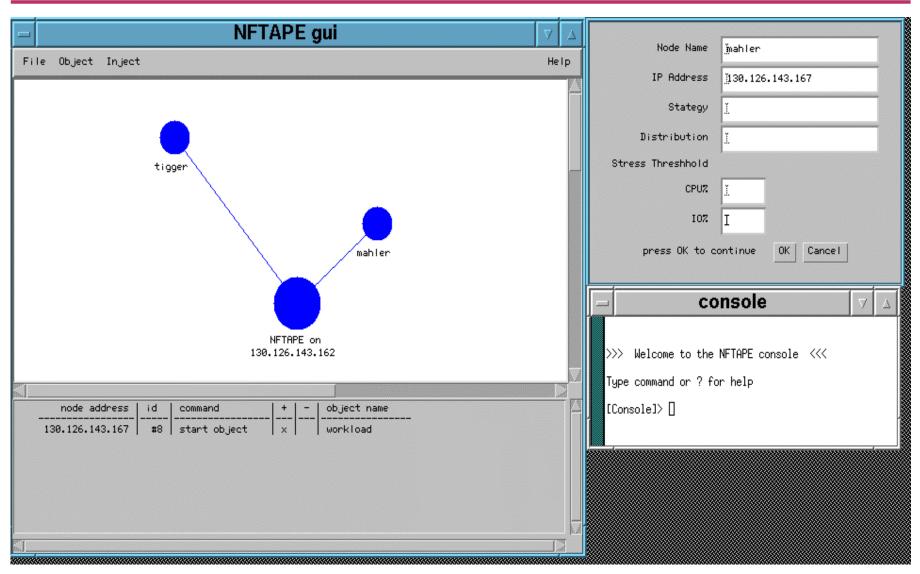
N-FTAPE





N-FTAPE User Interface





Validation of Simulation Using SWIFI



Dependability study of Myrinet networked system Simulated Myrinet Network - simulated fault injection (DEPEND) Real Myrinet Network - Software Implemented Fault Injection

- simulation does extremely well in modeling non faulty conditions (97%)
- reasonable well at predicting less severe injection results, e.g., a dropped message (95%)
- relatively low accuracy in predicting severe faults, e.g., interface hang (62%)

Reasons:

- simplification of the simulation model, e.g., the interaction between the components in the system - a host and the interface
- specification problems, e.g., not specified behavior for a response to an unaligned memory address
- impact of the simulation environment, e.g., the simulation engine and the executed software shared the same process and an error in the simulated software can corrupt variables belonging to the simulation engine

Summary & Conclusions





Framework for Design and Evaluation of Dependable systems:

- Hierarchical Methodology for Accurate fault Modeling
- horizontal hierarchy
 - system decomposition into subsystems at the same abstraction level
 - demonstrated cache-based RAID storage systems
- vertical hierarchy
 - system decomposition into subsystems at different abstraction levels, e.g., device level, circuit level, chip level and system level.
 - demonstrated Myrinet network system
- effects of low-level faults are propagated to the higher levels using fault dictionaries
- developed library of components to simulate systems with different characteristics, e.g., different network systems - Myrinet, ServerNet (by Tandem)



Network Fault Tolerance and Performance Evaluator

Software Implemented Fault Injection

- non-intrusive method of introducing faults to:
 - memory locations, CPU registers, and I/O (including network) to affect application and/or operating system
- injection under a realistic workload (real programs or synthetic workload)
- ability to mimic real fault conditions
- demonstrated:
 - Integrity S2 fault -tolerant system (by Tandem)
 - Sun systems Sun OS, Sun Solaris (on sun4m), Sun Solaris (on sun4u ongoing)
 - Windows NT study of fault impacts in device drivers ServerNet network,

Hardware Implemented Fault Injection

- non-intrusive injection into signals transmitted through the network
- high speed of operation (system clock from 500Mhz to several GHz)
- triggers and injection patterns stored in FPGA
- the manufactured prototype is under test

Collaboration with JPL



Methods and tools to design and evaluate systems with enough detail and accuracy to reveal design flows and assess system dependability early in the design process.



Early design phase

Framework for Design and Evaluation of Dependable systems

- CAD environment to evaluate design via simulation
- hierarchical methodology for accurate fault modeling
- simulated fault injection experiments
- evaluate effectiveness of fault tolerance mechanisms (e.g., coverage, detection latency)

Work with JPL

- we collaborate with JPL in using DEPEND framework for conducting experiments with low level fault injection and N-FTAPE for supporting fault injection to actual systems
 - DEPEND will be ported soon to JPL
 - N-FTAPE is being ported to JPL
- our students will work remotely and in JPL site to ensure correct operation of the tools (currently two students are working with JPL)
- target systems will be identified with close collaboration with the JPL scientists and engineers (e.g., a VxWorks based networked system)



Prototype phase

Network Fault Tolerance and Performance Evaluator

Software Implemented Fault Injection

- non-intrusive method of introducing faults
- injection under a realistic workload
- measures: error latency and propagation times, detection distributions

JPL should provide

- computing resources, including hardware (e.g., computing platforms) and software (e.g., applications and development tools)
- details about selected computing platforms, including configuration of computation nodes, type of operating system, I/O, network
- contact person(s) familiar with specifics of JPL environment and capable of providing necessary technical assistance